Grammar Acquisition using Human-like Memory Bounds

William Schuler Dept. of Linguistics, The Ohio State University

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A history of results show recall declines if constituents center-embed (Miller & Isard, 1964, inter alia):

- (1) The jeweler made [the ring that won [the prize that was given at the fair]]. (sentence recalled correctly)
- (2) [The prize that [the ring that [the jeweler] made] won] was given at the fair. (sentence recalled less accurately)

A history of results show recall declines if constituents center-embed (Miller & Isard, 1964, inter alia):

- (1) The jeweler made [the ring that won [the prize that was given at the fair]]. (sentence recalled correctly)
- (2) [The prize that [the ring that [the jeweler] made] won] was given at the fair. (sentence recalled less accurately)
- There are more common examples, but still difficult:
- (3) If [either [both [the power is on] and the door is closed] or the power is off] then the bell will stop.

Corpus results show human language is highly depth-constrained (Karlsson, 2007; Schuler et al., 2010):

Switchboard (transcribed spontaneous speech):

memory capacity (no punct)	sentences	coverage
no stack memory	26,201	28.38%
1 stack element	53,740	58.21%
2 stack elements	85,068	92.14%
3 stack elements	91,890	99.53%
4 stack elements	92,315	99.99%
5 stack elements	92,328	100.00%
TOTAL	92,328	100.00%

Corpus results show human language is highly depth-constrained (Karlsson, 2007; Schuler et al., 2010):

Wall Street Journal (newspaper text):

memory capacity (no punct)	sentences	coverage	
no stack memory	127	0.32%	
1 stack element	3,550	8.90%	
2 stack elements	25,948	65.06%	
3 stack elements	38,948	97.66%	
4 stack elements	39,866	99.96%	
5 stack elements	39,883	100.00%	
TOTAL	39,883	100.00%	

EEG show increased theta, gamma coherence during center embedding (left anterior-posterior), consistent with storage of incomplete signs (Weiss et al., 2005; van Schijndel et al., 2015):



(Johnson-Laird, 1983; Abney & Johnson, 1991; Gibson, 1991; Resnik, 1992; Stabler, 1994; Lewis & Vasishth, 2005)

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No-fork option:



Fork option:



(Johnson-Laird, 1983; Abney & Johnson, 1991; Gibson, 1991; Resnik, 1992; Stabler, 1994; Lewis & Vasishth, 2005)



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(Johnson-Laird, 1983; Abney & Johnson, 1991; Gibson, 1991; Resnik, 1992; Stabler, 1994; Lewis & Vasishth, 2005)



No-join option:



Join option:



(Johnson-Laird, 1983; Abney & Johnson, 1991; Gibson, 1991; Resnik, 1992; Stabler, 1994; Lewis & Vasishth, 2005)



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For example: start with zero incomplete signs

Left-corner parsers model human-like memory bounds For example: fork, no join (now <u>one</u> incomplete sign: NP/N)

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For example: no fork, no join (still one incomplete sign: NP/RC)



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Left-corner parsers model human-like memory bounds For example: fork, no join (now two incomplete signs: NP/RC, NP/N)



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Left-corner parsers model human-like memory bounds For example: no fork, join (now one incomplete sign: NP/V)



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For example: no fork, no join (still one incomplete sign: S/VP)



Left-corner parsing is as accurate as bottom-up parsing

van Schijndel et al. (2013):

System	Precision	Recall	F-score
Roark 2001 (CNF)	86.6	86.5	86.5
Left-corner (CNF, beam width 500)	86.6	87.3	87.0
Left-corner (CNF, beam width 2000)	87.8	87.8	87.8
Left-corner (CNF, beam width 5000)	87.8	87.8	87.8
Petrov Klein (CNF)	88.1	87.8	88.0
Petrov Klein (not CNF)	88.3	88.6	88.5

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 $\mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{1..t-1} \, w_{1..t-1}) = \mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{t-1})$

Markov assump.

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$$P(\vec{s}_t w_t \mid \vec{s}_{1.t-1} w_{1.t-1}) = P(\vec{s}_t w_t \mid \vec{s}_{t-1})$$

= $P(\vec{s}_t \mid \vec{s}_{t-1}) \cdot P(w_t \mid \vec{s}_t)$

Markov assump. transition & emit

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$$\begin{split} \mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{1.t-1} \, w_{1.t-1}) &= \mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{t-1}) & \text{Markov assump.} \\ &= \mathsf{P}(\vec{s}_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid \vec{s}_t) & \text{transition \& emit} \\ &= \mathsf{P}(f_t j_t \, \vec{a}_t \, \vec{b}_t \, p_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid p_t) & \text{left-corner trans.} \end{split}$$

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 $\begin{aligned} \mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{1.t-1} \, w_{1.t-1}) &= \mathsf{P}(\vec{s}_t \, w_t \mid \vec{s}_{t-1}) & \text{Markov assump.} \\ &= \mathsf{P}(\vec{s}_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid \vec{s}_t) & \text{transition \& emit} \\ &= \mathsf{P}(f_t j_t \, \vec{a}_t \, \vec{b}_t \, p_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid p_t) & \text{left-corner trans.} \end{aligned}$

Unconstrained, this would cost $O(K^{2 \times D \times 2})$, (*K* is the number of categories, *D* is the maximum depth).

 $\mathsf{P}(\vec{s}_t w_t \mid \vec{s}_{1,t-1} w_{1,t-1}) = \mathsf{P}(\vec{s}_t w_t \mid \vec{s}_{t-1})$ Markov assump. $= \mathsf{P}(\vec{s}_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid \vec{s}_t)$ transition & emit $= \mathsf{P}(f_t \, i_t \, \vec{a}_t \, \vec{b}_t \, p_t \mid \vec{s}_{t-1}) \cdot \mathsf{P}(w_t \mid p_t)$ left-corner trans. $= \mathsf{P}_F(f_t \mid \vec{s}_{t-1}) \cdot$ fork (boolean) $\mathsf{P}_{I}(j_{t} \mid f_{t} \vec{s}_{t-1})$ join (boolean) $\mathsf{P}_{\mathsf{A}}(\vec{a}_t \mid f_t \mid i_t \mid \vec{s}_{t-1})$ a categories $\mathsf{P}_{R}(\vec{b}_{t} \mid f_{t} \mid i_{t} \mid \vec{a}_{t} \mid \vec{s}_{t-1})$ b categories $\mathsf{P}_{P}(p_{t} \mid \vec{b}_{t} \vec{s}_{t-1})$. part of speech word model $\mathsf{P}_W(w_t \mid p_t)$

But left-corner constraints are more efficient...

In each \vec{a}_t , \vec{b}_t , only the lowest a_t^d and b_t^d are free (the rest are copied / null):

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In each \vec{a}_t , \vec{b}_t , only the lowest a_t^d and b_t^d are free (the rest are copied / null): $P_A(\vec{a}_t | f_t j_t \vec{s}_{t-1}) =$

$$\begin{pmatrix} \prod_{d'=1}^{d-2} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^{d-1} = a_{t-1}^{d-1} \rrbracket \cdot \prod_{d'=d}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = -, j_t = + \\ \prod_{d'=1}^{d-1} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{-/-}(a_t^d \mid b_{t-1}^{d-1} a_{t-1}^d) \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = -, j_t = - \\ \prod_{d'=1}^{d-1} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^d = a_{t-1}^d \rrbracket & \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = - \\ \prod_{d'=1}^{d} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^d = a_{t-1}^d \rrbracket & \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = - \\ \prod_{d'=1}^{d} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{+/-}(a_t^{d+1} \mid b_{t-1}^d p_{t-1}) \cdot \prod_{d'=d+2}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = - \\ \end{pmatrix}$$

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where $d = \max\{d' | s_{t-1}^{d'} \neq -/-\}$ and $\llbracket \phi \rrbracket = 1$ iff ϕ otherwise 0.

- In each \vec{a}_t , \vec{b}_t , only the lowest a_t^d and b_t^d are free (the rest are copied / null): $P_A(\vec{a}_t | f_t j_t \vec{s}_{t-1}) =$
 - $\begin{cases} \prod_{d'=1}^{d-2} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^{d-1} = a_{t-1}^{d-1} \rrbracket \cdot \prod_{d'=d}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = -, j_t = + \\ \prod_{d'=1}^{d-1} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{-/-}(a_t^d \mid b_{t-1}^{d-1} a_{t-1}^d) \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = -, j_t = \\ \prod_{d'=1}^{d-1} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^d = a_{t-1}^d \rrbracket & \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = + \\ \prod_{d'=1}^{d} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \llbracket a_t^{d'} = a_{t-1}^d \rrbracket & \cdot \prod_{d'=d+1}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = + \\ \prod_{d'=1}^{d} \llbracket a_t^{d'} = a_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{+/-}(a_t^{d+1} \mid b_{t-1}^d p_{t-1}) \cdot \prod_{d'=d+2}^{D} \llbracket a_t^{d'} = -\rrbracket, & \text{if } f_t = +, j_t = \end{cases}$

 $\mathsf{P}_B(\vec{b}_t \mid f_t j_t \vec{a}_t \vec{s}_{t-1}) =$

 $\begin{cases} \prod_{d'=1}^{d-2} \llbracket b_t^{d'} = b_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{-/+}(b_t^{d-1} \mid b_{t-1}^{d-1} a_{t-1}^d) \cdot \prod_{d'=d}^{D} \llbracket b_t^{d'} = - \rrbracket, & \text{if } f_t = -, j_t = + \\ \prod_{d'=1}^{d-1} \llbracket b_t^{d'} = b_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{-/-}(b_t^d \mid a_t^d a_{t-1}^d) & \cdot \prod_{d'=d+1}^{D} \llbracket b_t^{d'} = - \rrbracket, & \text{if } f_t = -, j_t = - \\ \prod_{d'=1}^{d-1} \llbracket b_t^{d'} = b_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{+/+}(b_t^d \mid b_{t-1}^d p_{t-1}) & \cdot \prod_{d'=d+1}^{D} \llbracket b_t^{d'} = - \rrbracket, & \text{if } f_t = +, j_t = - \\ \prod_{d'=1}^{d-1} \llbracket b_t^{d'} = b_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{+/-}(b_t^{d+1} \mid a_t^{d+1} p_{t-1}) \cdot \prod_{d'=d+2}^{D} \llbracket b_t^{d'} = - \rrbracket, & \text{if } f_t = +, j_t = - \\ \prod_{d'=1}^{d} \llbracket b_t^{d'} = b_{t-1}^{d'} \rrbracket \cdot \mathsf{P}_{+/-}(b_t^{d+1} \mid a_t^{d+1} p_{t-1}) \cdot \prod_{d'=d+2}^{D} \llbracket b_t^{d'} = - \rrbracket, & \text{if } f_t = +, j_t = - \\ \end{bmatrix}$

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where $d = \max\{d' | s_{t-1}^{d'} \neq -/-\}$ and $\llbracket \phi \rrbracket = 1$ iff ϕ otherwise 0.

So left-corner parser transitions cost only $O(K^{2 \times D} \times 2 \times 2 \times K^2)$.

Labels can be unified using priors across depth levels



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